Abstract. The recent claim by Smylie [1992] to have detected the Slichter modes of the Earth's inner core rests on what appears to be a remarkable agreement between theory and observation. However, the theoretical eigenperiods which are used by Smylie conflict significantly with all previously published periods for the Slichter modes, both for non-rotating and rotating Earth models. A closer examination of the theory used in these calculations reveals the use of static Love numbers to represent the response of the inner core and mantle to dynamics in the liquid core. We here show that the use of dynamic Love numbers restores the eigenperiods to those obtained using standard seismological theory and consequently destroys agreement between these periods and the claimed observations.

Introduction

The Slichter triplet is a curiosity in the family of Earth's normal modes. Unlike the rest of the seismic normal modes, the restoring force on the inner core is primarily gravitational rather than elastic, and the triplet has never been observed following an earthquake [Rydelek and Knopoff, 1984]. From a classification point of view, it is now generally known as $S^2_1$ [cf. Crossley, 1975b], denoting the first overtone $n=1$ of the degree $l=1$ motions.

Adopting the conventions $u \propto e^{i(\omega t+\phi)}$ for the displacement field $u$, $\phi$ positive eastward (with rotation) and using positive frequencies $\omega$, it is clear that $m=+1$ is a westward wave motion on a sphere, $m=0$ is axisymmetric and $m=-1$ is eastward. On a rotating sphere, $m=+1$ is therefore retrograde (against rotation) and has a higher frequency (shorter period). The opposite is true for the prograde mode $m=-1$. Curiously, Smylie [1992] adopts the reverse terminology for prograde and retrograde motions. To first order in rotation, the frequency of the $m=0$ wave is unchanged, but second order and higher order perturbation theory also shifts the period of this mode from the non-rotating value.

Because of the high frequency of the elastic normal modes compared to the sidereal rotation frequency, first or second order perturbation theory is usually considered adequate to accurately find the Coriolis splitting of the degenerate eigenfrequencies. Due to the relatively weak gravitational restoring force on the inner core, perturbation theory is less applicable for the long period (several hours) of the Slichter modes [Crossley, 1975b; Smith 1976; Dahlen and Sailor, 1979].

Love numbers have generally been used to represent the elastic response of the Earth to tidal forcing, and as such are generally considered to be static, representing the response of the Earth at periods much longer than the elastic normal modes. However, as pointed out by Pekeris and Accad [1972], the tidal Love numbers do in fact vary with frequency at long periods (several hours) for an Earth model with a stably stratified liquid core, due to resonances at the periods of internal gravity waves in the fluid. Considerable simplification can be made in the dynamics of the liquid core by using load Love numbers to represent the response of the inner core and mantle [Smylie, 1988; Rochester and Peng, 1990; Crossley et al., 1991].

The Love numbers computed for $l=1$, particularly those for the inner core boundary (ICB), have resonances close to those of the Slichter periods for the whole Earth and therefore static values cannot be used to represent the response of the inner core and mantle. Indeed on physical grounds it should be immediately obvious that, because the Slichter modes are primarily motions of the inner core, one cannot focus on the dynamic response of the liquid outer core and ignore the the inertia term in the computation of the ICB Love numbers when these Love numbers explicitly incorporate the inner core oscillation. Unfortunately, Smylie [1988] missed this important point when he assumed that the inertial terms in the inner core and mantle were insignificant, and he took the deformation field therein to be static.

Rochester and Peng [1990] first discussed the calculation of the Slichter modes using the variational procedure with the subseismic approximation (SSA) and dynamic Love numbers for the inner core and mantle. Here we recompute the Slichter periods for a variety of Earth models using both direct integration and Love numbers. In order to reproduce Smylie's periods as closely as possible, we also used the subseismic approximation in two related forms. SSA-1 refers to the application of the subseismic approximation only in the body of the liquid core [Smylie and Rochester, 1981] and using the boundary conditions that apply for the full system. SSA-2 refers to a further stage of approximation, that used by Smylie et al. [1990], in which the SSA is applied also to the boundary conditions [cf. Crossley and Rochester, 1992].

$\Delta \rho_{\text{ICB}}$ and $N^2$

We begin by noting the relation between the density jump at the ICB ($\Delta \rho_{\text{ICB}}$) and the non-rotating Slichter eigenperiod $T_0$. We construct, beginning with PREM [Dzie-
wonski and Anderson, 1981], a suite of Earth models with liquid cores of different buoyancy periods $T_B = 2\pi/N$, where $N$ is the Brünt Väisälä frequency, and different values of $\Delta \rho_{ICB}$. In each model, the seismic velocities are unchanged throughout the Earth and for each new $T_B$ the mass of the Earth is also maintained. Then we integrated the equations of motion directly and obtained values of $T_0$.

The starting conditions at the Earth's centre have to be correctly satisfied to allow displacements of the inner core about the fixed centre of mass [Crossley, 1975a].

The results (Figure 1) indicate that outer core stability plays a significant role only when $\Delta \rho_{ICB} < 0.4 \ g \ cm^{-3}$ and that a strongly stable stratification can provide a gravitational restoring force even for negative density contrasts. For a neutral core, the Slichter period becomes infinite as $\Delta \rho_{ICB} \rightarrow 0$. We show our computed periods for 1066A [Gilbert and Dziewonski, 1975], PREM and CORE11 (Widmer et al., 1988). Also plotted are the periods for DG579, an unlisted model used by Smith [1976], and model 71BG of Smylie [1992], using respectively their quoted values of $\Delta \rho_{ICB}$ and $T_0$. Smylie's eigenperiods for 71BG, 1066A and CORE11 are much below the curve along which all other results are grouped.

An Earth model with a period $T_0$ as short as that quoted for 71BG requires $\Delta \rho_{ICB} = 1.26 \ g \ cm^{-3}$. This value is considered seismologically extremely unlikely from an analysis of a suite of elastic normal modes studied by Masters and Shearer [1990, Figure 1], which favours 0.475 $g \ cm^{-3}$.

Dynamic Love numbers

As discussed by Smylie et al. [1990], Crossley et al. [1991] and Rochester and Peng [1992], the use of Love numbers considerably simplifies core dynamics in the cases where the boundaries are elastic and/or the gravity effect at the surface (through the mantle eigenfunctions) is required.

Load Love numbers can be regarded as matching constants connecting the dynamic variables at the ICB and core mantle boundary (CMB). The 6th order equations are integrated for three trial solutions throughout the inner core, from the Earth's centre to the ICB. On applying the appropriate boundary conditions at the ICB, one obtains two independent pairs of load Love numbers, from which any of the regular variables (radial displacements, stresses or gravity variables) can be expressed. These Love numbers are then stored for future use.

The process is repeated for the mantle, integrating from the CMB to the Earth's surface where traditional boundary conditions are applied. Again two more pairs of independent Love numbers are obtained and stored. At this point, one goes back and integrates throughout the fluid core, with two trial solutions at a trial eigenfrequency for the four independent equations in the fluid, using the Love numbers where appropriate to construct the discriminant (based on continuity of radial displacement and normal stress at the CMB) for each trial eigenfrequency. The key question is whether or not the load Love numbers need be re-computed each time the outer core eigenfrequency is re-adjusted (dynamic Love numbers), or whether static (zero frequency) Love numbers computed once only are sufficient.

In principle, all Love numbers are dynamic since the equations integrated in the solid normally contain the inertial term $\omega^2 u$. Load Love numbers exhibit resonances that reflect eigensolutions of the restricted problem being addressed. For example, the ICB Love numbers have a resonance whenever there is a true eigensolution of a realistic inner core bathed in an infinite fluid of uniform density equal to the density on the fluid side of the ICB, since this density was embedded in the boundary condition used at the ICB to generate the Love numbers. Similarly, a CMB Love number shows resonances at the eigensolutions of a realistic shell (the mantle) filled inside with a fluid of uniform density equal to that on the fluid side of the CMB.

It can be seen in Figure 2 that in the neighbourhood of an isolated resonance $\omega_L$, the Love numbers are of the form $h(\omega) = h(0) + h_2[(1 - \omega^2/\omega_L^2)^{-1} - 1]$ where $h(\omega)$ is the dynamic Love number and $h(0)$ is the static Love number.
number. Only if \( \omega^2 < \omega_L^2 \) may we take \( h(\omega) \sim h(0) \). The
above expression for the Love number does not have to be
programmed into the computations, but arises naturally as
a result of including the inertial term in the equations of
motion.

We can now appreciate the significance of using dynamic
Love numbers whenever the anticipated eigenfrequency of
the complete system is close to a Love number resonance.
Since the ICB Love number resonance for 1066A is at \( T_L = 3.995 \) hr, it is close to the anticipated period of \( T = 4.599 \)
hr (Figure 2). Consequently it is essential to use dynamic
Love numbers for the Slichter modes.

Table 1 shows dynamic and static Love numbers for \( \chi \),
the reduced potential and \( d\phi/dr \), the derivative of the grav-
ity potential, for 3 Earth models and compares the results
to those of Smylie [1992]. We note first that the degree 1
Love numbers are extremely sensitive to the details of the
numerical methods used in the integration, which is suffi-
cient to explain the slight discrepancies between the vari-
ous authors for the same calculation. With this in mind,
it is quite clear that important conclusions can be drawn.
First, we have recovered Smylie's static Love numbers for
1066A and CORE11. This indicates that all authors agree,
within numerical error, with the method of integrating the
equations of motion in the limit of zero frequency.

Second, independent calculations (Crossley, Peng) con-
firm the Love numbers computed at the periods of the re-
spective non-rotating Slichter modes and are significantly
different from the static values, as to be expected from Fig-
ure 2. This difference explains the bulk of the discrepancy
between Smylie's computed periods and our new calcula-
tions which agree with standard seismological theory.

Coriolis Splitting

Before we can compare our final results to those of Smylie
[1992], we have to tackle the question of Coriolis splitting.
Dahlen and Sailor [1979] elegantly summarized the results
of second order perturbation theory in their analysis of
Dahlen and Sailor [1979] have extended the coupling chain to degree 5,
i.e. the displacement field is represented by harmonics \( S^m \).
Smylie [1992] uses SSA-2 with an unknown number of
terms to expand the variable \( \chi \) at the ICB and CMB.

Our final results for the Slichter eigenperiods are given
in Table 2. We denote by \( T_P \) the prograde \((m = -1)\), \( T_R \) the retrograde \((m = +1)\), and \( T_C \) the
central \((m = 0)\) peak. Our split eigenperiods are computed
using the second order perturbation formulae of Dahlen
and Sailor [1979].

Notice that for the full equations, direct and Love num-
ber methods yield identical results, showing correct im-
plementation of the algorithms. Necessarily, the dynamic
Love number calculations also agree with previous values,
allowing for the sensitivity of the Slichter periods to de-
ts of the integration method. SSA-1 yields little change
from the full equations, whereas SSA-2 underestimates the
correct eigenperiod by about 10% due to problems with
the SSA at the CMB [Crossley and Rochester, 1992]. The
periods using static Love numbers are 40% too low.

Results for several Earth models are plotted in Figure 3,
which is analogous to that shown by Smylie [1992]. Note
that with dynamic Love numbers, not only would the ‘ob-
served’ eigenperiods require an unacceptably high ICB den-
sity contrast, but also the splitting is greater than that ob-
tained theoretically and observationally by Smylie [1992,
equation (1)]. This implies that if the observational
triplet identified by him were to be confirmed, the peaks
are unlikely to be associated with a co-rotating physical
oscillation of the Earth.

<table>
<thead>
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<th>TABLE 1 - Slichter mode eigenperiods, model 1066A</th>
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</table>

(1) Periods in hours. Rotating eigenperiods are by 2nd
order splitting except for Smylie (full rotation).
(2) Equations F = full, SSA-1, SSA-2; Method D = direct,
LN = dynamic Love number, SLN = static Love number;
Author C = Crossley, MD = Masters, Dahlen (independent
personal communications, May 1992), S = Smylie.

(3) The period used by Smylie is not known; his Love
numbers for \( d\phi/dr \) are defined with the opposite sign to us.
We have verified Smylie's eigenperiods to within 2%, indicating to our satisfaction that we have correctly understood his numerical procedures. We have therein demonstrated that the use of static rather than dynamic Love numbers is the main reason he obtains significantly different Slichter eigenperiods from published and here reconfirmed values. The substantial correction necessary to Smylie's eigenperiods leads to complete disagreement with the periods he identifies in the data and destroys his claim to have detected the Slichter modes.

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**References**


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